



*Opinionated*  
Lessons  
in Statistics

*by Bill Press*

*#24 Goodness of Fit*

Good time now to review the universal rule-of-thumb (meta-theorem):

**Measurement precision improves with the amount of data  $N$  as  $N^{1/2}$**

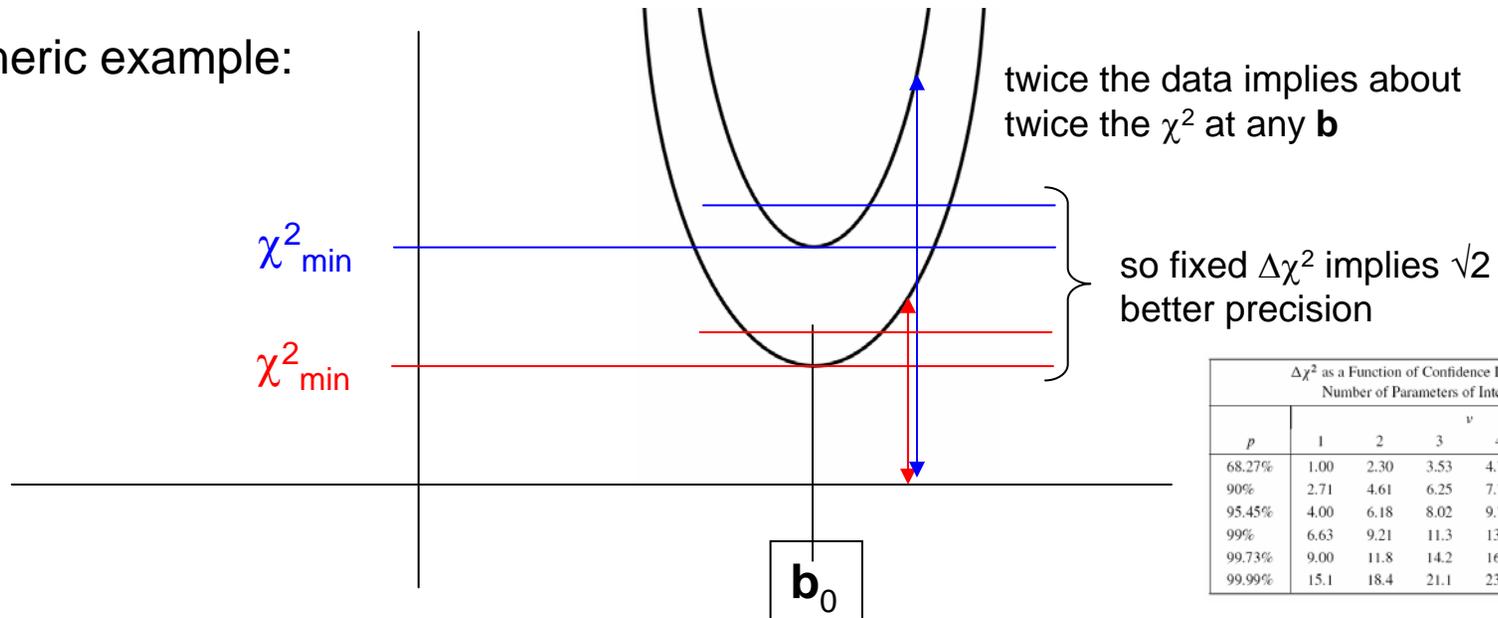
Simple example:

“measurement precision” = “accuracy of a fitted parameter”

$$\mu = \frac{1}{N} \sum_{i=1}^N x_i$$

$$\text{Var}(\mu) = \frac{1}{N^2} \text{Var} \left( \sum_{i=1}^N x_i \right) = \frac{1}{N^2} [N \text{Var}(x)] = \frac{1}{N} \text{Var}(x)$$

Generic example:



| $p$    | $\Delta\chi^2$ as a Function of Confidence Level $p$ and Number of Parameters of Interest $\nu$ |      |      |      |      |      |
|--------|---|------|------|------|------|------|
|        | $\nu$   |      |      |      |      |      |
|        | 1   | 2    | 3    | 4    | 5    | 6    |
| 68.27% | 1.00  | 2.30 | 3.53 | 4.72 | 5.89 | 7.04 |
| 90%    | 2.71  | 4.61 | 6.25 | 7.78 | 9.24 | 10.6 |
| 95.45% | 4.00  | 6.18 | 8.02 | 9.72 | 11.3 | 12.8 |
| 99%    | 6.63  | 9.21 | 11.3 | 13.3 | 15.1 | 16.8 |
| 99.73% | 9.00  | 11.8 | 14.2 | 16.3 | 18.2 | 20.1 |
| 99.99% | 15.1  | 18.4 | 21.1 | 23.5 | 25.7 | 27.9 |

## Let's discuss Goodness of Fit (at last!)

Until now, we have **assumed** that, for **some** value of the parameters  $\mathbf{b}$  the model  $y(\mathbf{x}_i|\mathbf{b})$  is correct.

That is a very Bayesian thing to do, since Bayesians start with an EME set of hypotheses. It also makes it difficult for Bayesians to deal with the notion of a model's **goodness of fit**.

So we must now again become frequentists for a while!

Suppose that the model  $y(\mathbf{x}_i|\mathbf{b})$  does fit. This is the **null hypothesis**.

Then the “statistic”  $\chi^2 = \sum_{i=1}^N \left( \frac{y_i - y(\mathbf{x}_i|\mathbf{b})}{\sigma_i} \right)^2$  is the sum of  $N$   $t^2$ -values.  (not quite)

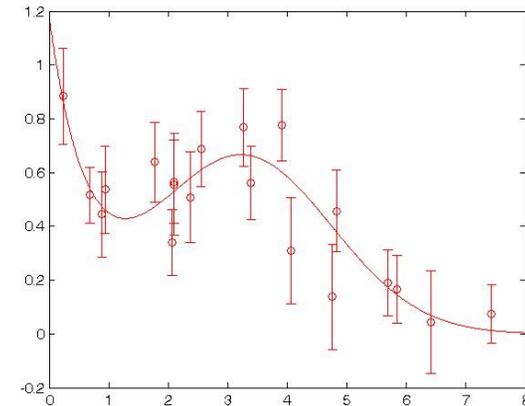
So, if we imagine repeated experiments (which Bayesians refuse to do), the statistic should be distributed as  $\text{Chisquare}(N)$ .

If our experiment is very unlikely to be from this distribution, we consider the model to be disproved. In other words, it is a p-value test.

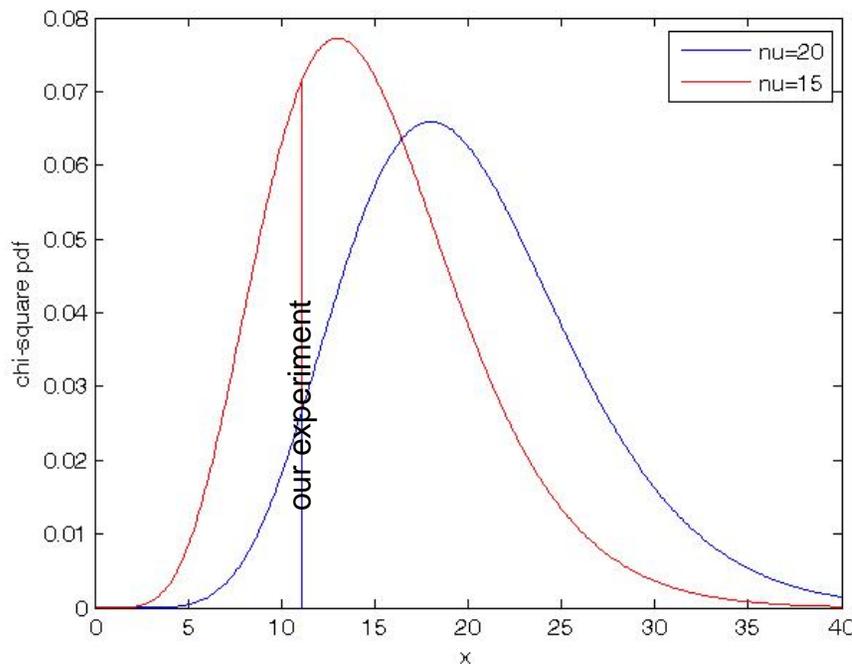
How is our fit by this test?

In our example,  $\chi^2(\mathbf{b}_0) = 11.13$

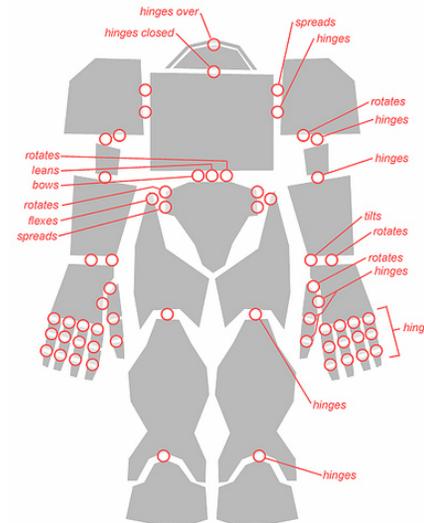
This is a bit unlikely in  $\text{Chisquare}(20)$ , with (left tail)  $p=0.0569$ .



In fact, if you had many repetitions of the experiment, you would find that their  $\chi^2$  is not distributed as  $\text{Chisquare}(20)$ , but rather as  $\text{Chisquare}(15)$ ! Why?



the magic word is:  
“degrees of freedom” or DOF



**Degrees of Freedom: Why is  $\chi^2$  with  $N$  data points “not quite” the sum of  $N$   $t^2$ -values? Because DOFs are reduced by constraints.**

First consider a hypothetical situation where the data has linear constraints:

$$t_i = \frac{y_i - \mu_i}{\sigma_i} \sim N(0, 1)$$

joint distribution on all the  $t$ 's, if they are independent

$$p(\mathbf{t}) = \prod_i p(t_i) \propto \exp\left(-\frac{1}{2} \sum_i t_i^2\right)$$

$\chi^2$  is squared distance from origin  $\sum t_i^2$

Linear constraint:

$$\sum_i \alpha_i y_i = C = \langle C \rangle = \sum_i \alpha_i \mu_i$$

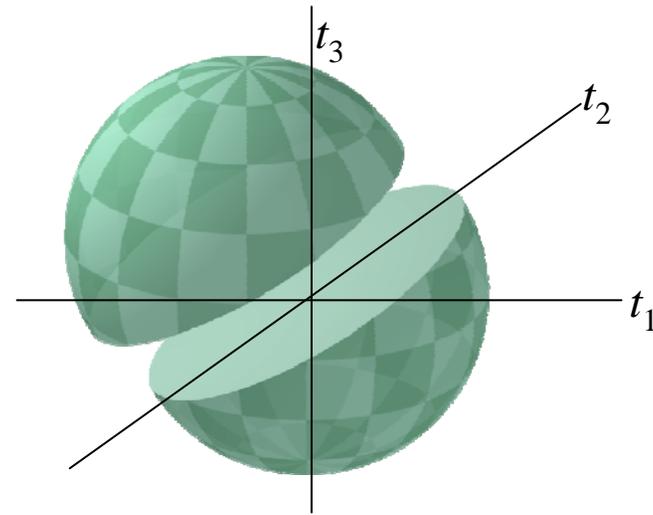
$$C = \sum_i \alpha_i (\sigma_i t_i + \mu_i)$$

$$= \sum_i \alpha_i \sigma_i t_i + C$$

$$\text{So, } \sum_i \alpha_i \sigma_i t_i = 0$$

a hyper plane through the origin in  $t$  space!

Constraint is a plane cut through the origin. Any cut through the origin of a sphere is a circle.



So the distribution of distance from origin is the same as a multivariate normal “ball” in the lower number of dimensions. Thus, each linear constraint reduces  $\nu$  by exactly 1.

We don't have explicit constraints on the  $y_i$ 's. But as we let the  $y_i$ 's wiggle around (within the distribution of each) we want to keep the MLE estimate  $\mathbf{b}_0$  (the parameters) fixed so as to see how  $\chi^2$  is distributed for this MLE – not for all possible  $\mathbf{b}$ 's. (20 wiggling  $y_i$ 's, 5  $b_i$ 's kept fixed.)

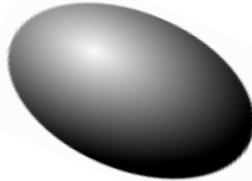
So by the implicit function theorem, there are  $M$  (number of parameters) approximately linear constraints on the  $y_i$  's. So  $\nu = N - M$ , the so-called number of degrees of freedom (d.o.f.).

Review:

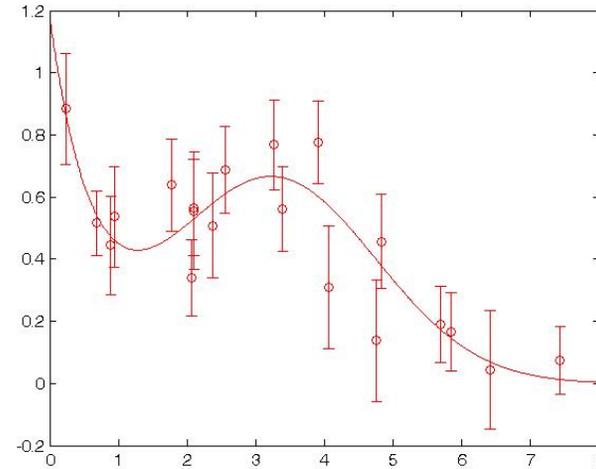
1. Fit for parameters by minimizing

$$\chi^2 = \sum_{i=1}^N \left( \frac{y_i - y(\mathbf{x}_i | \mathbf{b})}{\sigma_i} \right)^2$$

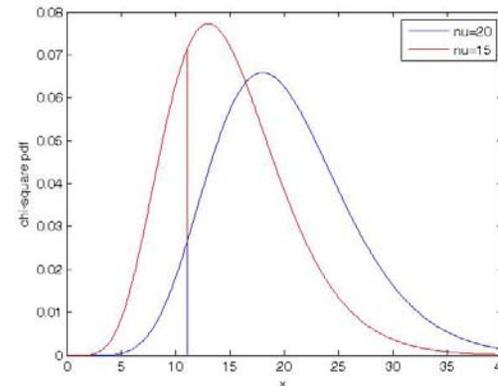
2. (Co)variances of parameters, or confidence regions, by the change in  $\chi^2$  (i.e.,  $\Delta\chi^2$ ) from its minimum value  $\chi^2_{\min}$ .



3. Goodness-of-fit (accept or reject model) by the p-value of  $\chi^2_{\min}$  using the correct number of DOF.



| $\Delta\chi^2$ as a Function of Confidence Level $p$ and Number of Parameters of Interest $\nu$ |       |      |      |      |      |      |
|---|-------|------|------|------|------|------|
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## Don't confuse typical values of $\chi^2$ with typical values of $\Delta\chi^2$ !

Goodness-of-fit with  $\nu = N - M$  degrees of freedom:

we expect  $\chi_{\min}^2 \approx \nu \pm \sqrt{2\nu}$

this is an RV over the population of different data sets (a frequentist concept allowing a p-value)

Confidence intervals for parameters  $\mathbf{b}$ :

we expect  $\chi^2 \approx \chi_{\min}^2 \pm O(1)$

this is an RV over the population of possible model parameters for a single data set, a concept shared by Bayesians and frequentists

**How can  $\pm O(1)$  be significant when the uncertainty is  $\pm \sqrt{2\nu}$  ?**

Answer: Once you have a particular data set, there is no uncertainty about what its  $\chi_{\min}^2$  is.

Let's see how this works out in scaling with  $N$ :

$\chi^2$  increases linearly with  $\nu = N - M$

$\Delta\chi^2$  increases as  $N$  (number of terms in sum), but also decreases as  $(N^{-1/2})^2$ , since  $\mathbf{b}$  becomes more accurate with increasing  $N$  :

$$\Delta\chi^2 \propto N(\delta b)^2, \quad \delta b \propto N^{-1/2} \quad \Rightarrow \quad \Delta\chi^2 \propto \text{const}$$

quadratic, because at minimum

universal rule of thumb